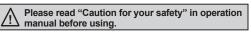
Small and light, common type

Features

- Easy to mount at a narrow space with small size and light weight.
- Convenient to adjust the sensitivity by external sensitivity adjustment contol.(Diffuse reflective type only)
- Easy to mount by screw type in mounting hole.
- Reverse power polarity protection circuit.







Specifications

Model		BM3M-TDT	BM1M-MDT	BM200-DDT		
Sensing type		Through-beam	Retroreflective	Diffuse reflective		
Sensing distance		3m	0.1 to 1m *1	200mm ^{×2}		
Sensing target		Opaque materials of Min. ø8mm	Opaque materials of Min. ø60mm	Translucent, Opaque materials		
Hysteresis		_		Max. 10% at rated settingdistance		
Response time		Max. 3ms				
Power supply		12-24VDC ±10%(Ripple P-P : Max. 10%)				
Current consumption		Max. 45mA	Max. 40mA			
Light source		Infrared LED(940nm)				
Sensitivity adjustment		Fixed		Adjustable VR		
Operation mode		Dark ON		Light ON(Dark ON: Option)		
Control output		NPN open collector output •Load voltage : Max. 30VDC •Load current : Max. 100mA •Residual voltage : Max. 1V				
Protection circuit		Reverse polarity protection				
Indication		Operation indicator : Red LED				
Insulation resistance		Min. 20MΩ(at 500VDC megger)				
Noise resistance		±240V the square wave noise(pulse width : 1μs) by the noise simulator				
Dielectric strength		1,000VAC 50/60Hz for 1minute				
Vibration		1.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours				
Shock		500m/s²(50G) in each of X, Y, Z directions for 3 times				
	Ambient illumination	Sunlight: Max. 11,0001x Incandescent lamp: Max. 3,0001x				
Environ- ment	Ambient temperature	-10 to 60°C, storage : -25 to 70°C				
	Ambient humidity	35 to 85%RH, storage : 35 to 85%RH				
Material		Case : ABS, Sensing part : Acryl(Retroreflective: PC)				
Cable		ø4mm, 3-wire, Length : 2m(Emitter of through-beam type: ø4mm, 2-wire, Length : 2m) (AWG22, Core diameter : 0.08mm, Numner of cores : 60, Insulator out diameter : ø1.25mm)				
Acce- ssories	Individual	_	Reflector(MS-2)	VR adjustment driver		
	Common	Mounting bracket, Bolts/nuts				
Approval		C€				
Unit weight		Approx. 170g	Approx. 105g	Approx. 88g		

X1: It is mounting distance between sensor and reflector MS-2 and it is same when MS-5 is used. It is detectable under 0.1m.

A-36 Autonics

X2: It is for Non-glossy white paper(200×200mm)

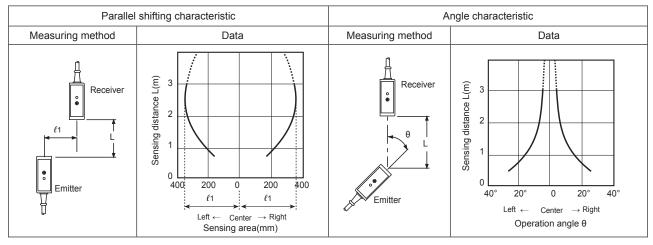
 $[\]ensuremath{\mathbb{X}}$ The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

Amplifier Built-in type for General Purpose

■ Feature data

O Through-beam type

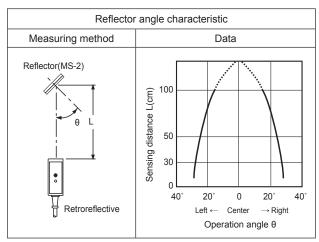
• BM3M-TDT



BM1M-MDT

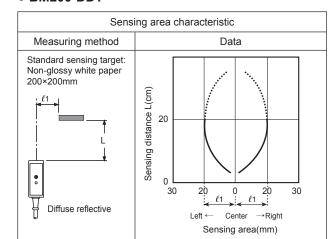
Paralle	shifting characteristic	Sensor angle characteristic		
Measuring method	Data	Measuring method	Data	
Reflector(MS-2) to the second of the secon	(ma) 100 100 100 100 100 100 100 100 100 10	Reflector(MS-2)	$(c) 100 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	

• BM1M-MDT



O Diffuse reflective type

• BM200-DDT



(A) Photo electric

(B) Fiber optic

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F)

(G)

(G) Connector/ Socket

(H) Temp. controller

> SSR/ Power controller

(J) Counter

(K) Timer

meter

Tacho/ Speed/ Pulse meter

(N) Display unit

> Sensor controller

(P) Switching power supply

(Q) Stepping motor& Driver&Controller

(R) Graphic/ Logic

(S) Field network device

device

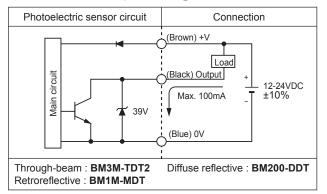
(T) Software

(U) Other

Autonics A-37

BM Series

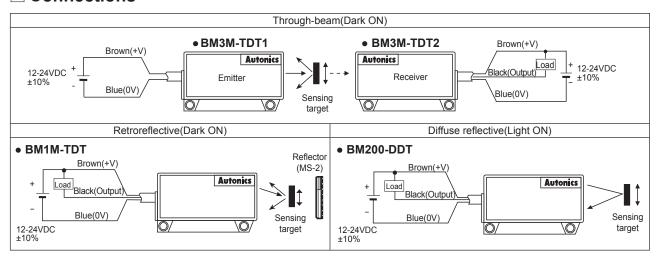
Control output diagram



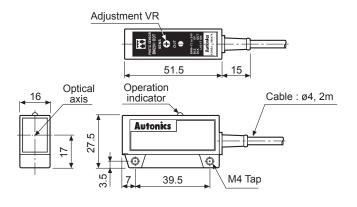
Operation mode

Operation mode		Light ON		
Receiver operation	Received light			
Treceiver operation	Interrupted light			
Operation indicator	ON			
(red LED)	OFF			
Transistor output	ON			
Transision output	OFF			
Operation mode	Dark ON			
Desciver energtion	Received light			
Receiver operation	Interrupted light			
Operation indicator	ON			
(red LED)	OFF			
Transistor output	ON			
าาสาเอเจเปา บนเคนเ	OFF			

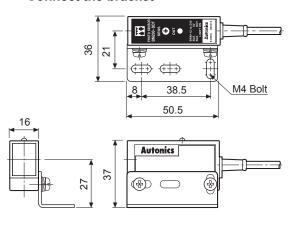
Connections





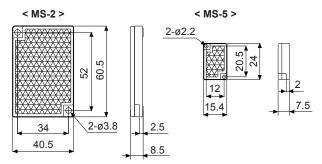


Connect the bracket

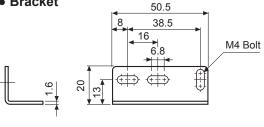


(unit: mm)

Reflector



Bracket



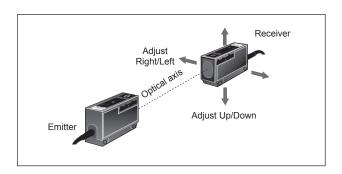
A-38

Amplifier Built-in type for General Purpose

■ Mounting and sensitivity adjustment

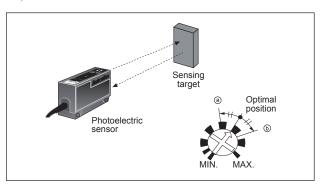
Through-beam type

- Supply the power to the photoelectric sensor, after setting the emitter and the receiver facing each other.
- Set the receiver in center of position in the middle of the operation range of indicator adjusting the receiver or the emitter right and left, up and down.
- 3. After adjustment, check the stability of operation putting the object at the optical axis.
- ※ If the sensing target is translucent body or smaller than ø8mm, it can be missed by sensor cause light penetrate it.



O Diffuse reflective type

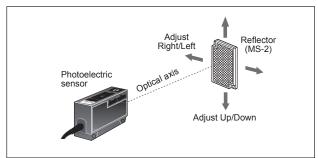
- 1. The sensitivity should be adjusted depending on a sensing target or mounting place.
- Set the target at a position to be detected by the beam, then turn the adjustment VR until position (a) where the operation indicator turns ON from min. position of the adjustment VR.
- 3. Take the target out of the sensing area, then turn the adjustment VR until position (b) where the the operation indicator turns ON. If the indicator dose not turn ON, max. position is (b).
- 4. Set the adjustment VR at the center of two switching position (a), (b).



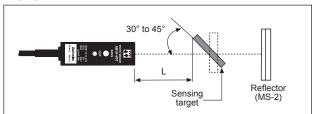
%The sensing distance indicated on specification chart is for 200×200mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.

Retroreflective type

- Supply the power to the photoelectric sensor, after setting the photoelectric sensor and the reflector(MS-2) in face to face.
- Set the photoelectric sensor in the position which indicator turns on, as adjusting the reflector or the sensor right and left, up and down.
- 3. Fix both units tightly after checking that the unit detects the target.
- ※If using more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.



※If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photoelectric sensor. Therefore put enough space between the target and the photoelectric sensor or the surface of the target should be installed at angle of 30° to 45° against optical axis.



If the mounting place is too narrow, please use MS-5 instead of MS-2.



(A) Photo electric

(B) Fiber optic

> (C) Door/Area

(D) Proximity sensor

(E) Pressure sensor

> F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

> (J) Counter

> > K)

L) Panel

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

Sensor controller

(P) Switching power supply

(Q) Stepping motor& Driver&Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Software

(U) Other

Autonics A-39